

Episode 7

Energy Relations for Conservative Systems of Particles

ENGN0040: Dynamics and Vibrations

Allan Bower, Yue Qi

**School of Engineering
Brown University**

Topics for todays class

Energy relations for conservative systems of particles

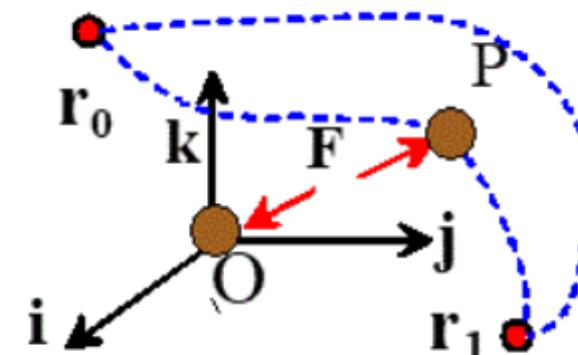
1. Conservative, non-conservative and workless forces
2. Potential energy of a conservative force
3. Work-Power-PE-KE relation for a conservative system of particles
4. Applications

4.2 Energy relations for conservative systems of particles

4.2.1 Conservative, non-conservative and workless forces

Recall: Work done by a force

$$W = \int_{\underline{r}_0}^{\underline{r}_1} \underline{F} \cdot d\underline{r}$$



Definition For a "conservative" force W is equal for all paths from $\underline{r}_0 \rightarrow \underline{r}_1$



Conservative

- Gravity
- Electrostatic forces
- Inter-molecular forces
- Forces exerted by springs



- Non-Conservative
- Friction
 - Air resistance



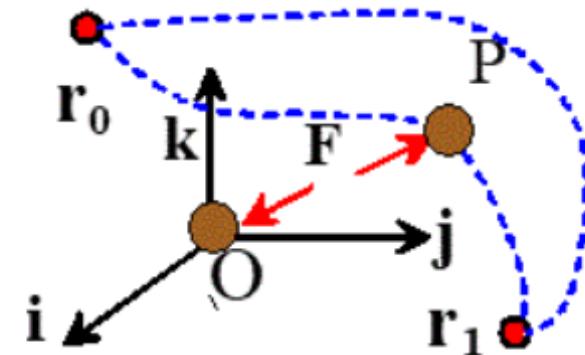
- Workless
- Lift force
 - Reaction forces
 - Lorenz force

$W=0$ for a "workless" force

4.2.2 Potential energy of a conservative force

Definition

$$\bar{U}(\underline{r}) = - \int_{\underline{r}_0}^{\underline{r}} \underline{F} \cdot d\underline{r} + C$$



\underline{r}_0 & C are arbitrary : choose them to make \bar{U} simple

Inverse relation

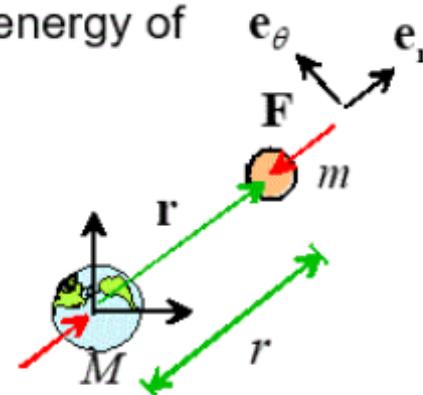
$$\underline{F} = -\nabla \bar{U} = - \left\{ \frac{\partial \bar{U}}{\partial x} \underline{i} + \frac{\partial \bar{U}}{\partial y} \underline{j} + \frac{\partial \bar{U}}{\partial z} \underline{k} \right\}$$

Note - signs !

4.2.3: Example: Calculating the potential energy of gravity (between planets)

$$\mathbf{F} = -\frac{GMm}{r^2} \mathbf{e}_r$$

$$G = 6.674 \times 10^{-11} \text{ m}^3 \text{kg}^{-1} \text{s}^{-2}$$



Formula

$$U = - \int_{r_0}^r \underline{F} \cdot d\underline{r} + C$$

Do integral in $\{\underline{e}_r, \underline{e}_\theta\}$ basis

$$U(r) = - \int_{r_0 \underline{e}_r}^{r \underline{e}_r} -\frac{GMm}{r^2} \underline{e}_r \cdot d\underline{r} \underline{e}_r + C$$

$$= \int_{r_0}^r \frac{GMm}{r^2} dr + C = \left[-\frac{GMm}{r} \right]_{r_0}^r + C$$

$$U = -\frac{GMm}{r} + \boxed{\frac{GMm}{r_0} + C}$$

Choose $C = -GMm/r_0$

$$U = -\frac{GMm}{r}$$

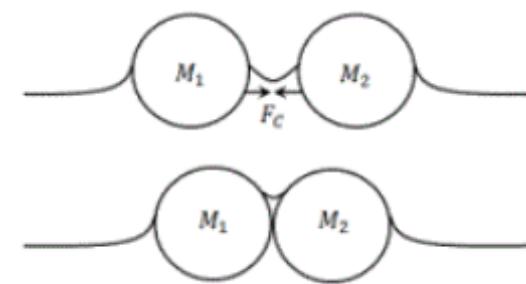
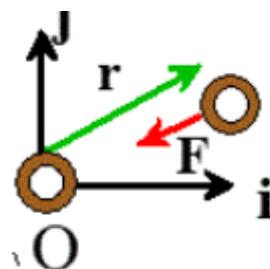
$$r = \sqrt{x^2 + y^2 + z^2}$$

4.2.4: Example: The potential energy of two neighboring Cheerios floating in milk is

$$U \approx E_0 \log\left(\frac{r}{L_0}\right) \quad r = \sqrt{x^2 + y^2}$$

where E_0, L_0 are constants

Find a formula for the force acting between them



Formula $F = -\nabla U$

Use chain rule

$$F = - \left\{ \frac{\partial U}{\partial r} \frac{\partial r}{\partial x} \hat{i} + \frac{\partial U}{\partial r} \frac{\partial r}{\partial y} \hat{j} \right\}$$

Note $\frac{\partial r}{\partial x} = \frac{1}{2} \frac{1}{\sqrt{x^2+y^2}} 2x = \frac{x}{r}$ $\frac{\partial r}{\partial y} = \frac{y}{r}$

$$F = \underbrace{\frac{\partial U}{\partial r}}_{\text{magnitude}} \left\{ - \underbrace{\frac{(x\hat{i} + y\hat{j})}{r}}_{\text{Unit vector - direction}} \right\} = \frac{\partial U}{\partial r} \left(- \frac{\hat{r}}{|\hat{r}|} \right)$$

For cheerios $\frac{\partial U}{\partial r} = \frac{E_0}{r} \Rightarrow F = \frac{E_0}{|r|} \left(-\frac{r}{|r|} \right)$

In general for a PE of form $U(r)$

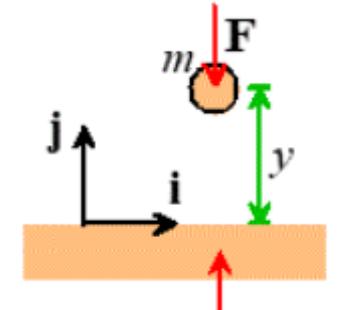
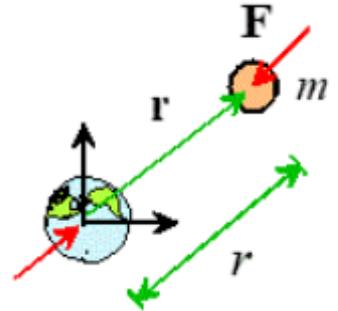
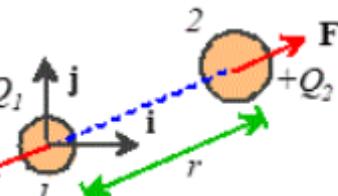
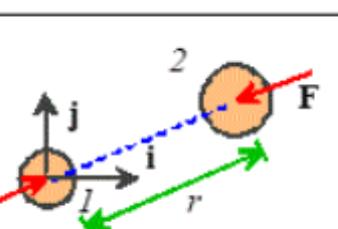
(1) Magnitude is $\frac{\partial U}{\partial r}$

(2) Direction is towards or away from origin

$\frac{\partial U}{\partial r} > 0 \Rightarrow$ force acts towards origin

$\frac{\partial U}{\partial r} < 0 \Rightarrow$ force acts away from origin

4.2.5: Table of potential energies for common forces

Type of force	Force vector	Potential energy	
Gravity acting on a particle near earth's surface	$\mathbf{F} = -mg\mathbf{j}$	$U = mgy$	
Gravitational force exerted on mass m by mass M at the origin	$\mathbf{F} = -\frac{GMm}{r^3}\mathbf{r}$	$U = -\frac{GMm}{r}$	
Force exerted by a spring with stiffness k and unstretched length L_0	$\mathbf{F} = -k(r - L_0)\frac{\mathbf{r}}{r}$	$U = \frac{1}{2}k(r - L_0)^2$	
Force acting between two charged particles	$\mathbf{F} = \frac{Q_1 Q_2}{4\pi\epsilon r^3}\mathbf{r}$	$U = \frac{Q_1 Q_2}{4\pi\epsilon r}$	
Force exerted by one molecule of a noble gas (e.g. He, Ar, etc) on another (Lennard Jones potential). a is the equilibrium spacing between molecules, and E is the energy of the bond.	$\mathbf{F} = 12 \frac{E}{a} \left[\left(\frac{a}{r} \right)^{13} - \left(\frac{a}{r} \right)^7 \right] \frac{\mathbf{r}}{r}$	$U = E \left[\left(\frac{a}{r} \right)^{12} - 2 \left(\frac{a}{r} \right)^6 \right]$	

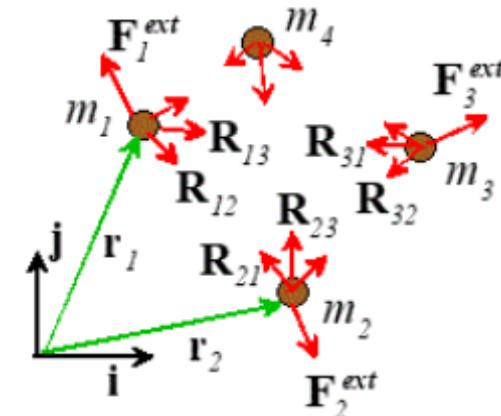
4.2.6 Energy equation for a conservative system

\mathbf{R}_{ij} Force exerted on particle i by particle j

\mathbf{F}_i^{ext} External force on particle i

\mathbf{r}_i Position of particle i

\mathbf{v}_i Velocity of particle i



$\underline{\mathbf{R}}_{ij}$: "Internal" forces $\underline{\mathbf{F}}_i^{ext}$: "external" forces

Definition system is conservative \Leftrightarrow all
 $\underline{\mathbf{R}}_{ij}$ are conservative

Let
$$\underline{\mathbf{R}}_{ij} = - \frac{\partial U_{ij}}{\partial \underline{\mathbf{r}}_i}$$

Definitions

① Total PE of system $U^{TOT} = \sum_{\text{internal forces}} U_{ij}$

② Total KE of system $T^{TOT} = \sum_{\text{Particles}} \frac{1}{2} m_i \cdot |\underline{V}_i|^2$

③ Power of external forces $P^{\text{ext}} = \sum_{\substack{\text{ext} \\ \text{forces}}} \underline{F}_i \cdot \underline{v}_i^{\text{ext}}$

④ Total external work done on system

$$\Delta W^{\text{ext}} = \int_{t_0}^{t_1} P^{\text{ext}} dt$$

Energy Equations

Power-Energy relation

$$P^{ext} = \frac{d}{dt} \left\{ U^{TOT} + T^{TOT} \right\}$$

Work-energy relation

$$\Delta W^{ext} = U_i^{TOT} + T_i^{TOT} - (U_0^{TOT} + T_0^{TOT})$$

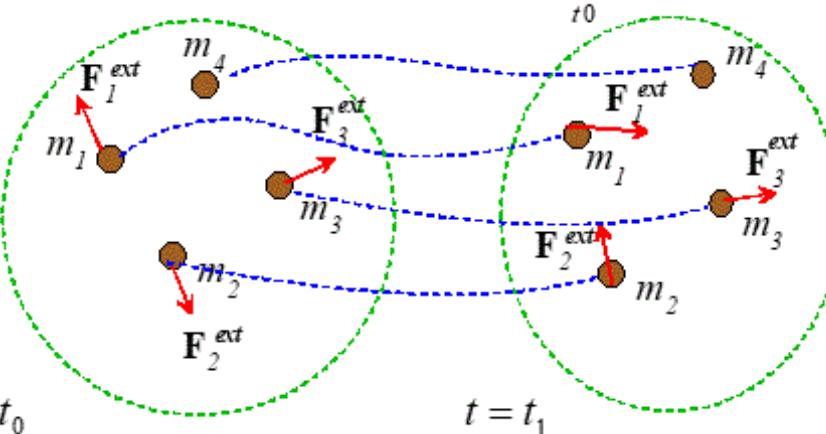
Special Case $\Delta W^{ext} = 0$

$$U_i^{TOT} + T_i^{TOT} = U_0^{TOT} + T_0^{TOT}$$

“Total energy is conserved”

External Power $P^{ext}(t)$

$$\text{External work } \Delta W^{ext} = \int_{t_0}^{t_1} P^{ext}(t) dt$$



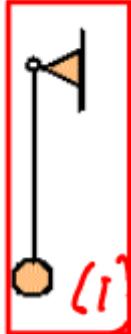
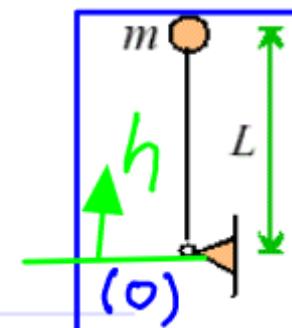
Total KE T_0^{TOT}

Total PE U_0^{TOT}

Total KE T_1^{TOT}

Total PE U_1^{TOT}

4.2.7: Example: The pendulum is stationary in its upright configuration. Following a small disturbance it falls over. Calculate the magnitudes of the velocity and acceleration of the mass when it reaches its lowest point.



Approach:

(1) System = earth + pendulum

(2) Conservative, no ext forces $\Rightarrow \Delta W^{\text{ext}} = 0$

$$\text{Hence } T_1 + U_1 = T_0 + U_0$$

$$\text{State (0)} \quad T_0 = 0 \quad U_0 = mgL$$

$$\text{State (1)} \quad T_1 = \frac{1}{2}mv^2 \quad U_1 = -mgL$$

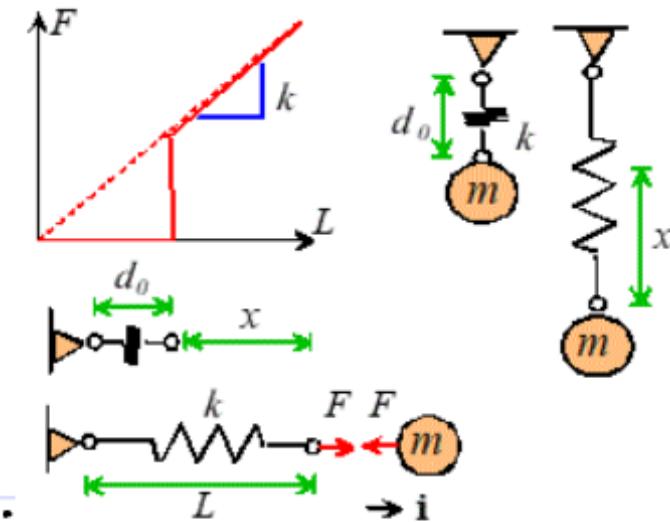
$$\Rightarrow \frac{1}{2}mv^2 - mgL = mgL \Rightarrow v = 2\sqrt{gL}$$

Acceleration Circular motion $\Rightarrow a = \frac{dV}{dt} \frac{t}{R} + \frac{V^2}{R} \stackrel{=0}{=} L$

$$\Rightarrow |a| = \frac{V^2}{L} = \frac{4gL}{L} \Rightarrow |a| = 4g$$

4.2.8: Example: A spring has the force-length relation shown.

- Find a formula for its potential energy
- A mass $m > kd_0 / g$ is suspended from the spring. Find the value of extension x in the static equilibrium configuration
- The mass released from rest with $x=0$. Find the maximum value of x and the acceleration of the mass at this instant.



$$(a) U = - \int_{d_0}^{L} F \cdot dL \quad F = -k(x+d_0)$$

$$\Rightarrow U = \int_0^x k(x+d_0) dx \Rightarrow U = \frac{1}{2}kx^2 + k d_0 x$$

(b) Statics

$$F_s = mg \Rightarrow k(x+d_0) = mg$$

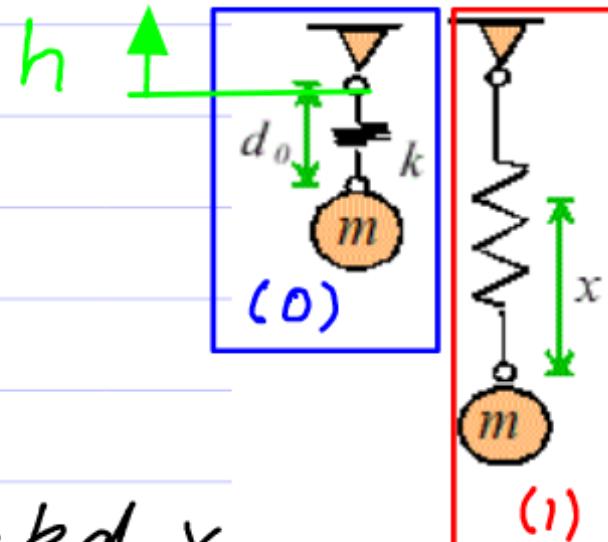
$$\Rightarrow x = \frac{mg}{k} - d_0$$



(c) System = earth + spring + mass

Conservative, no ext forces

$$T_1 + U_1 = T_0 + U_0$$



$$(0) \quad T_0 = 0 \quad U_0 = -mgd_0$$

$$(1) \quad T_1 = 0 \quad U_1 = -mg(d_0+x) + \frac{1}{2}kx^2 + kd_0x$$

$$\Rightarrow -mg(d_0+x) + kx\left(\frac{x}{2} + d_0\right) = -mgd_0$$

$$\Rightarrow x = 2 \left(\frac{mg}{k} - d_0 \right)$$

Twice static deflection

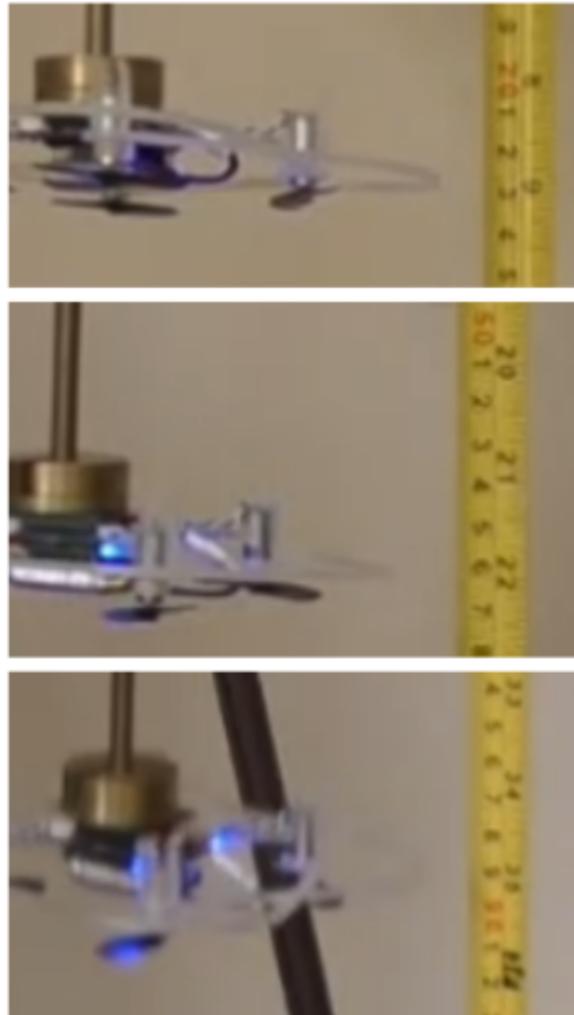
Acceleration Use $F = ma$

$$ma = F_s - mg = k(x+d_0) - mg$$

$$\Rightarrow a = g - \frac{k d_0}{m}$$



Spring Drop Experiment



Coiled spring
 $h = 22.5\text{cm}$

Predicted to be equal

33.5cm

Static equilibrium
 $h = 56\text{cm}$

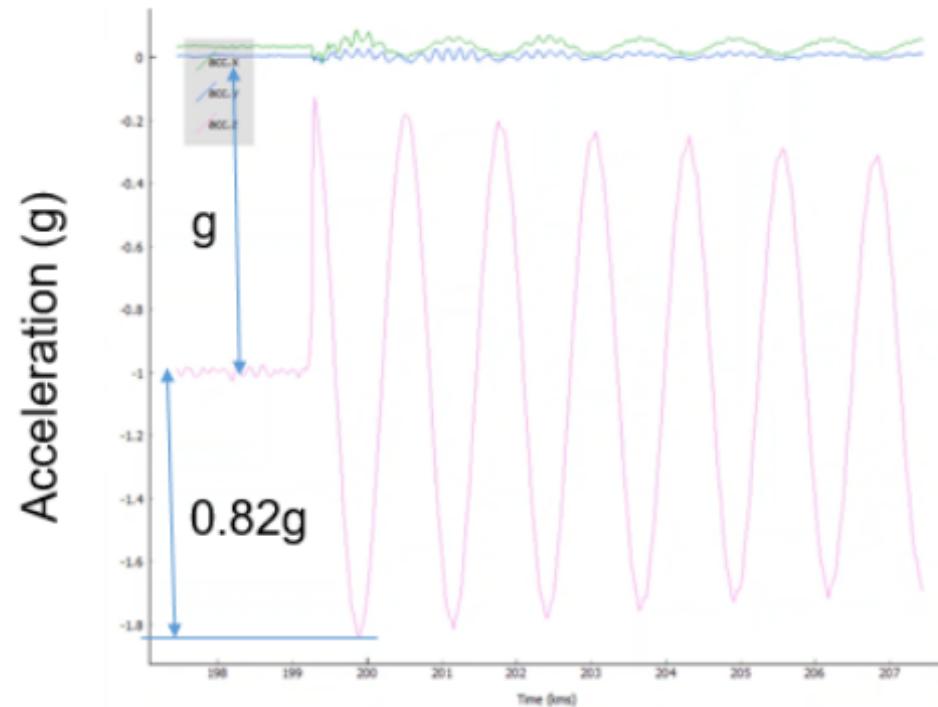
33cm

Max deflection
 $h = 89\text{cm}$

Prediction

Spring stiffness: 3.5 N/m
 Spring length at zero force 6.5cm
 Total mass 142.8 grams

$$a = g - kd_0 / m = 0.84g$$



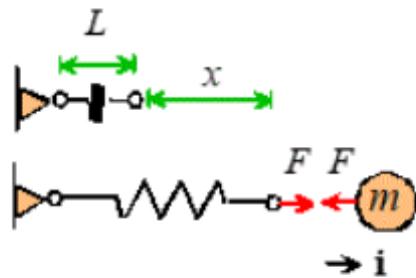
4.2.8: Example: A dynamic climbing rope has a force-elongation relation that can be approximated by $F = F_0 \varepsilon^{3/2}$

- (a) Find a formula for the potential energy of a rope with length L
- (b) A climber with mass m is tethered by a rope with length L . The climber falls a distance h before the rope begins to stretch, and is brought to rest as the rope stretches. Show that the fractional change in length of the rope ε is related to the fall factor $f = h/L$ by

$$f = \frac{2F_0}{5mg} \varepsilon^{5/2} - \varepsilon$$

- (c) Find the value of F_0 necessary to pass the UIAA standard

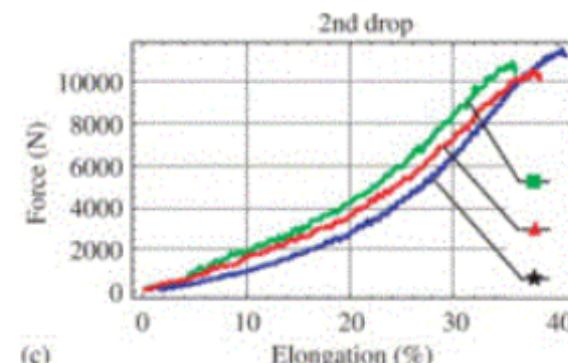
(a) Think of rope as nonlinear spring



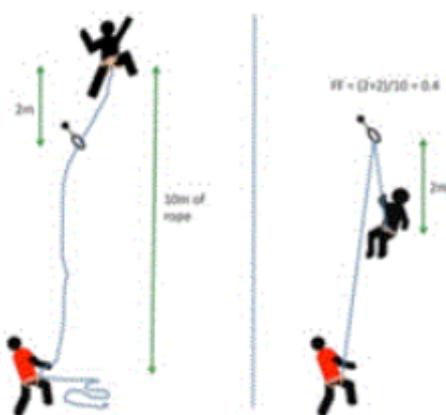
$$F = -F_0 \varepsilon^{3/2} \quad \varepsilon = x/L$$

$$U = - \int_{L_0}^L F \cdot dL = \int_0^x F_0 \left(\frac{x}{L} \right)^{3/2} dx$$

$$\Rightarrow U = \frac{2}{5} F_0 L \left(\frac{x}{L} \right)^{5/2} = \frac{2}{5} F_0 L \varepsilon^{5/2}$$



(c)



(b) System = earth + rope + climber

Datum

Conservative, no ext force

$$T_1 + U_1 = T_0 + U_0$$

$$(0) \quad T_0 = 0 \quad U_0 = 0$$

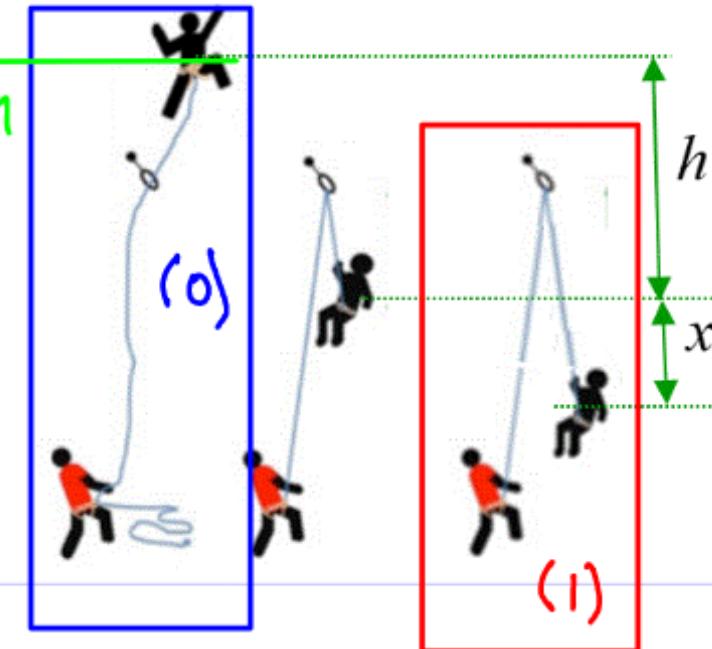
$$(1) \quad T_1 = 0$$

$$U_1 = -mg(h+x) + \frac{2}{5}F_0L\left(\frac{x}{L}\right)^{5/2}$$

$$\Rightarrow mgh = \frac{2}{5}F_0L\left(\frac{x}{L}\right)^{5/2} - mgx$$

$$\Rightarrow \frac{h}{L} = \frac{2}{5} \frac{F_0}{mg} \left(\frac{x}{L}\right)^{5/2} - \frac{x}{L}$$

$$\Rightarrow f = \frac{2}{5} \frac{F_0}{mg} \varepsilon^{5/2} - \varepsilon$$



(c) UIAA standard

for $m = 80 \text{ kg}$, $f = 1.75$: (a) $\varepsilon \leq 0.4$
 (b) Force in rope
 $< 12 \text{ kN}$

$$\text{We have } f = \frac{2}{5} \frac{F_0}{mg} \varepsilon^{5/2} - \varepsilon$$

Use (a) \Rightarrow

$$F_0 = \frac{5}{2} (f + \varepsilon) \frac{mg}{\varepsilon^{5/2}} = 42 \text{ kN}$$

Check (b) $F = F_0 \varepsilon^{3/2} = 11 \text{ kN}$

Postscript: ropes in example just pass standard

